



# Pushing Inference to the Sky: A Differentiable Forward Model for the 21 cm Global Signal (work in progress..)



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## 1. How does performing inference on the sky help?

- More faithful accounting of beam, FGs, and their degeneracies
- Fully exploit correlations in the data between LSTs

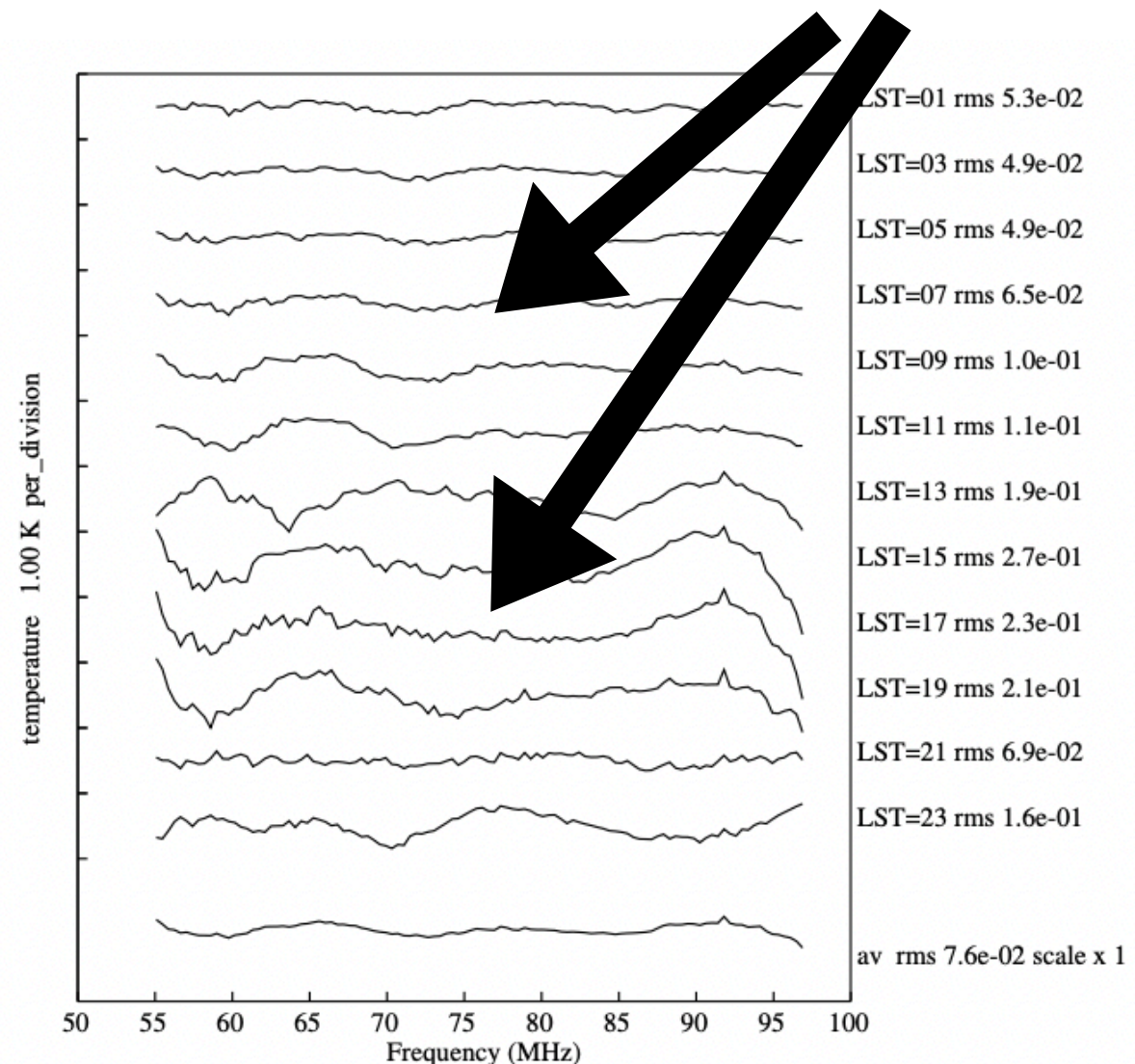
## 2. Is detection theoretically possible?

- Even in ideal circumstances, 21 cm global signal extraction is **highly degenerate** with FG spectral modes (c.f. Liu et al. 2012)
- Forward modeling of **flexible** but **regularized** sky + instrument models is key to a robust 21 cm GS constraint

# Why an end-to-end forward model?

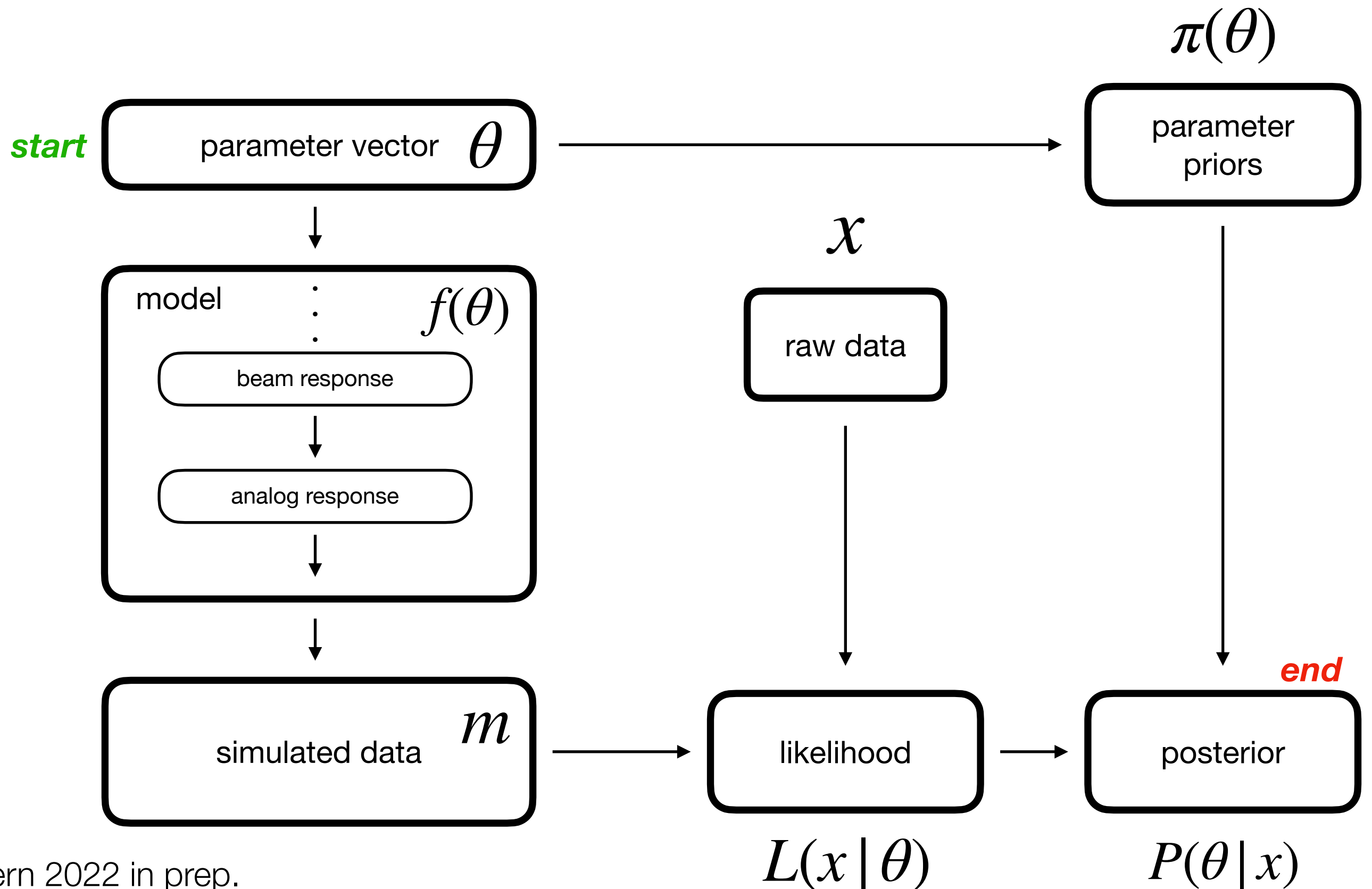
- Robust signal extraction must understand the joint posterior between the **beam**, **FG**, and **21 cm** signal
- This requires a data model that **starts on the sky**, as opposed to a spectrum-based data model
- Including the visibility sky integral in our data model allows us to fully (and properly) exploit correlations between LSTs

fully exploit correlations between LSTs



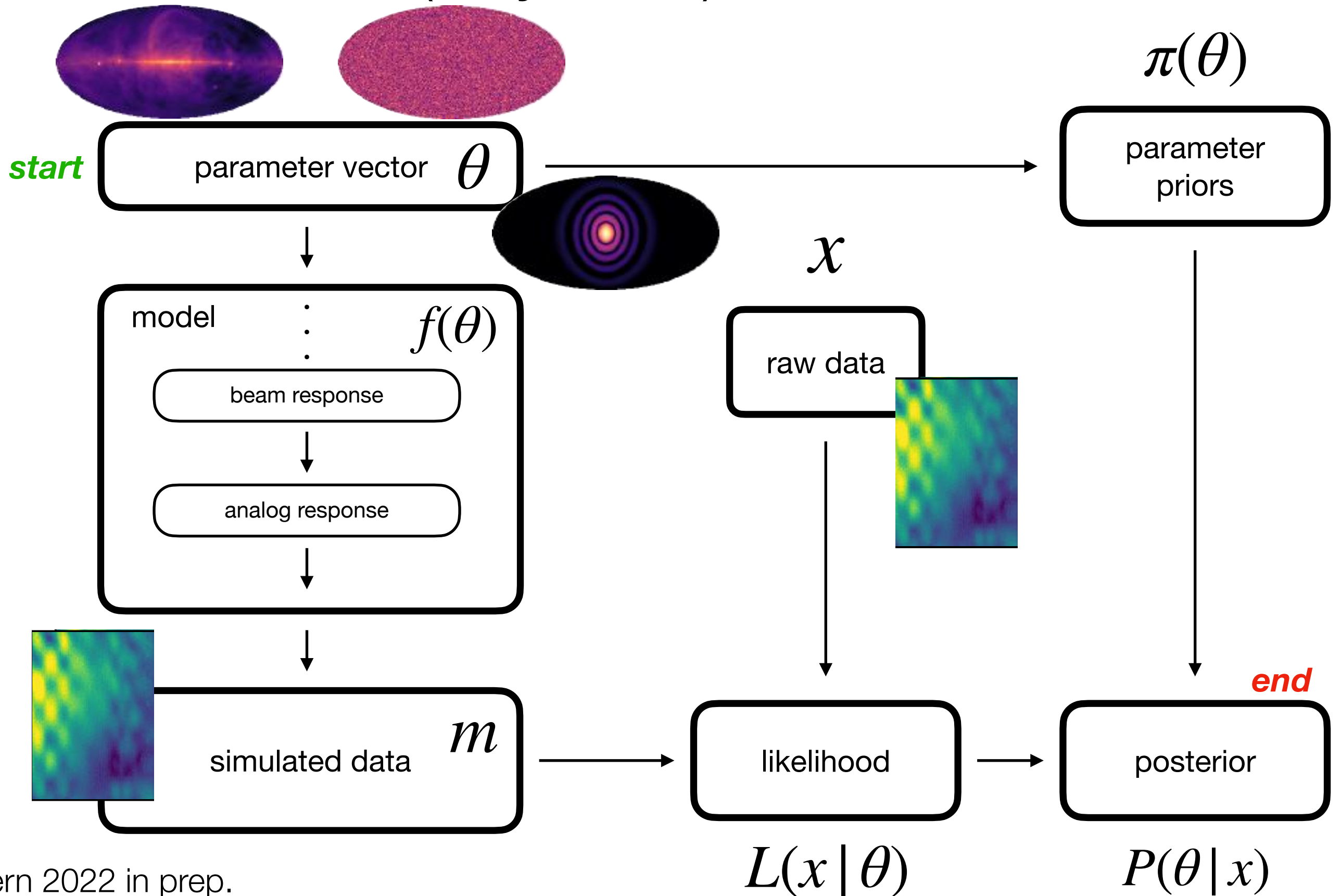
avrms 0.1308

# What is a (Bayesian) forward model?

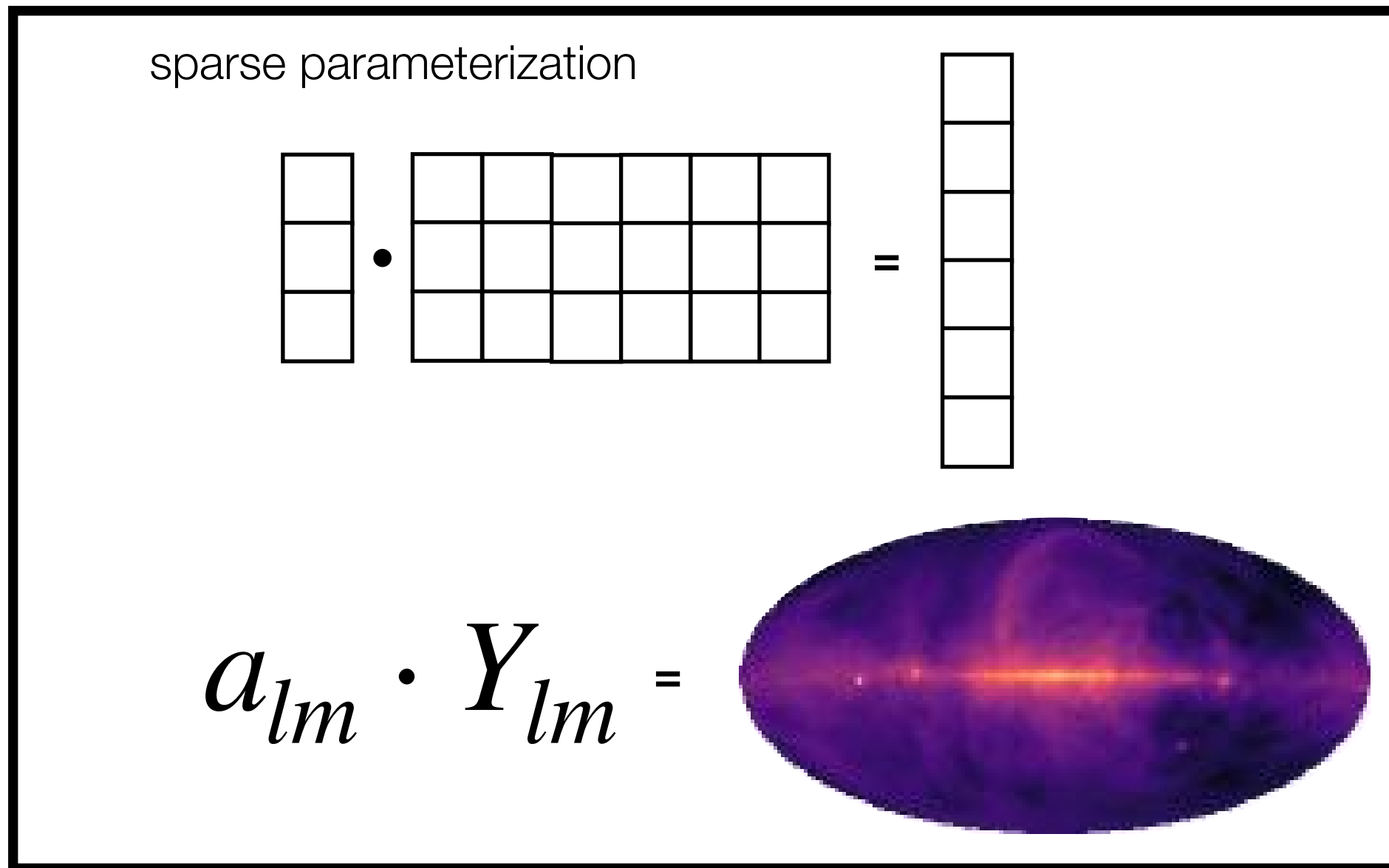




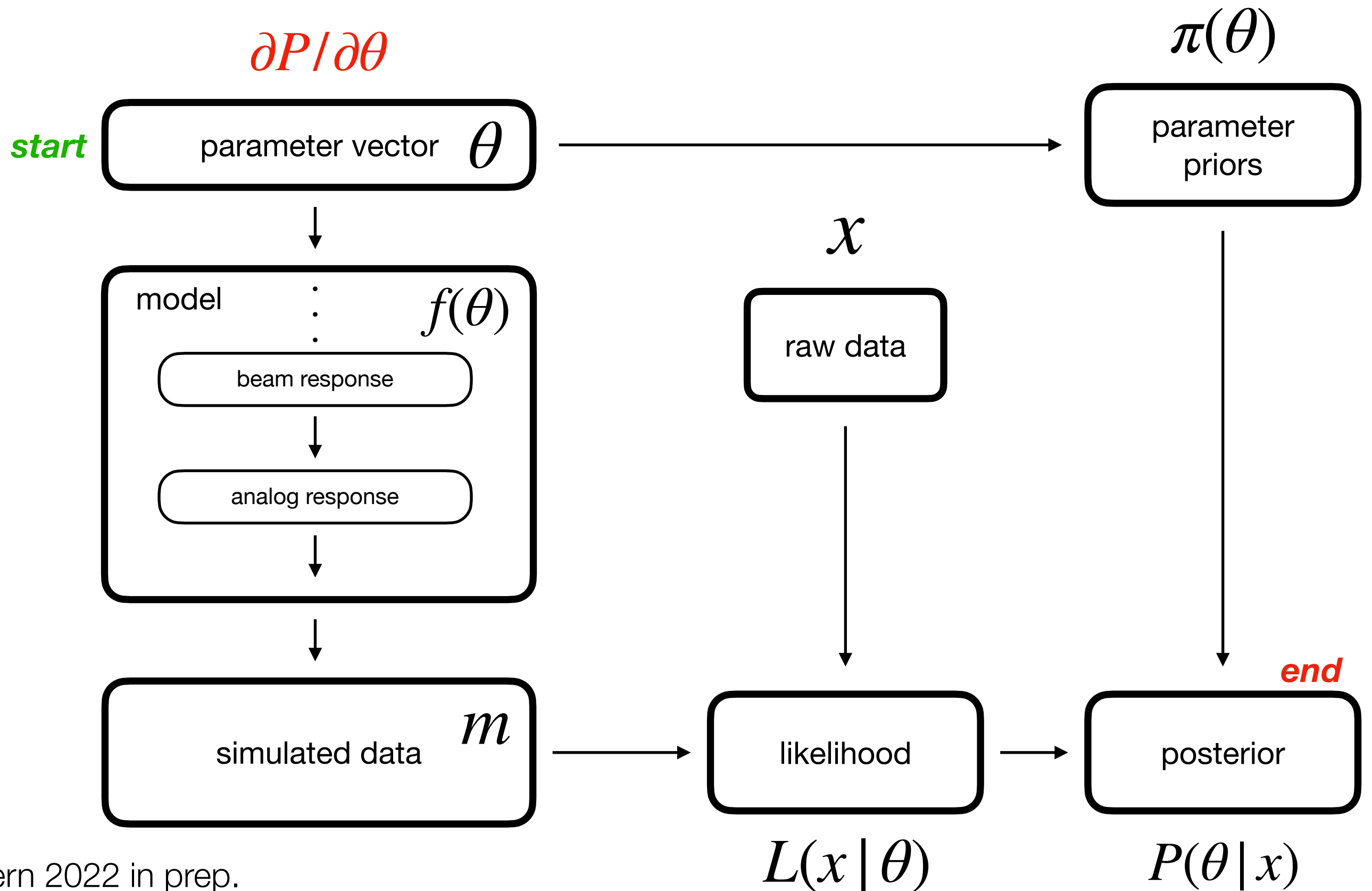
# What is a (Bayesian) forward model?



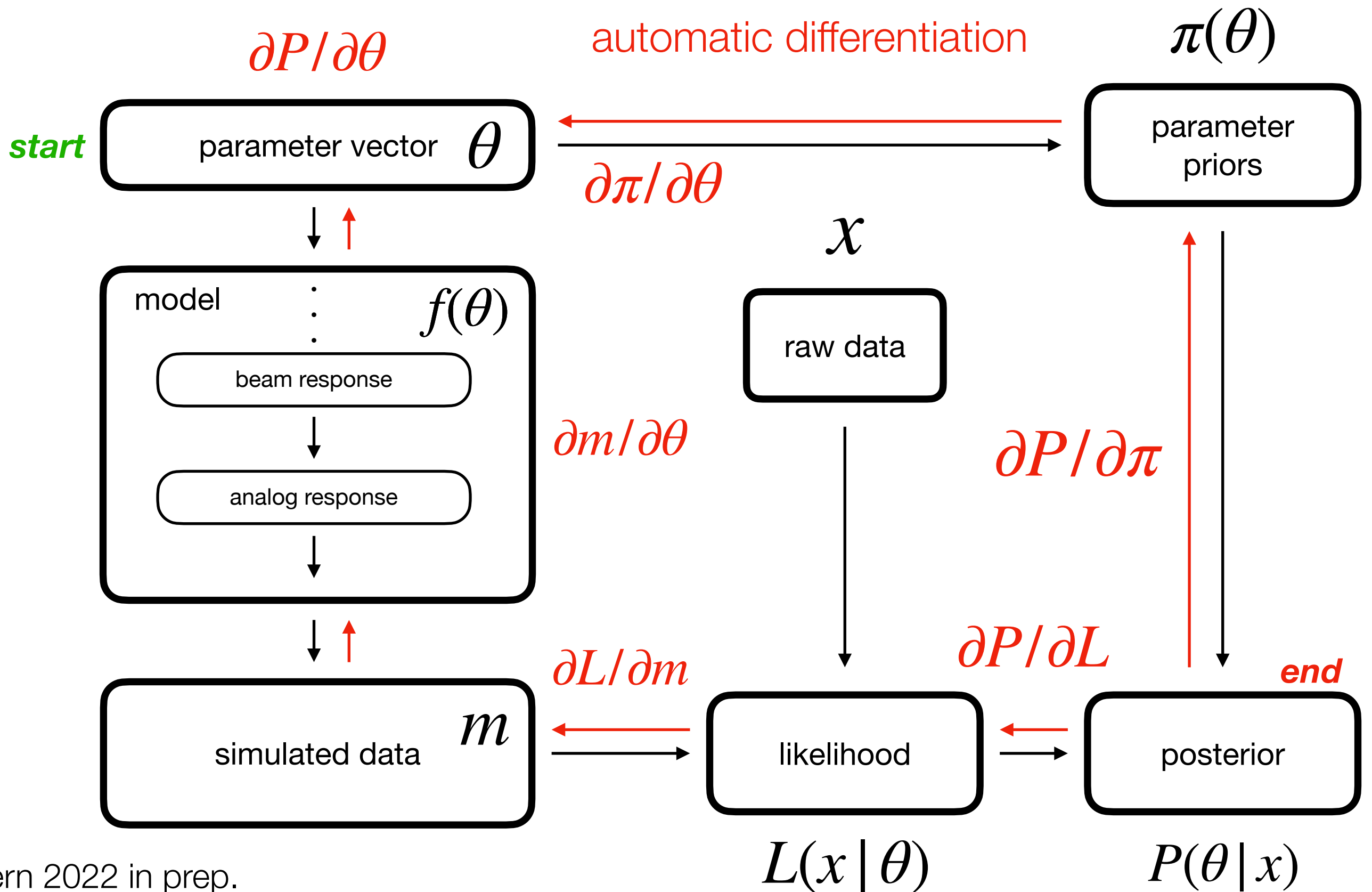
# What is a (Bayesian) forward model?



# How to make it differentiable?



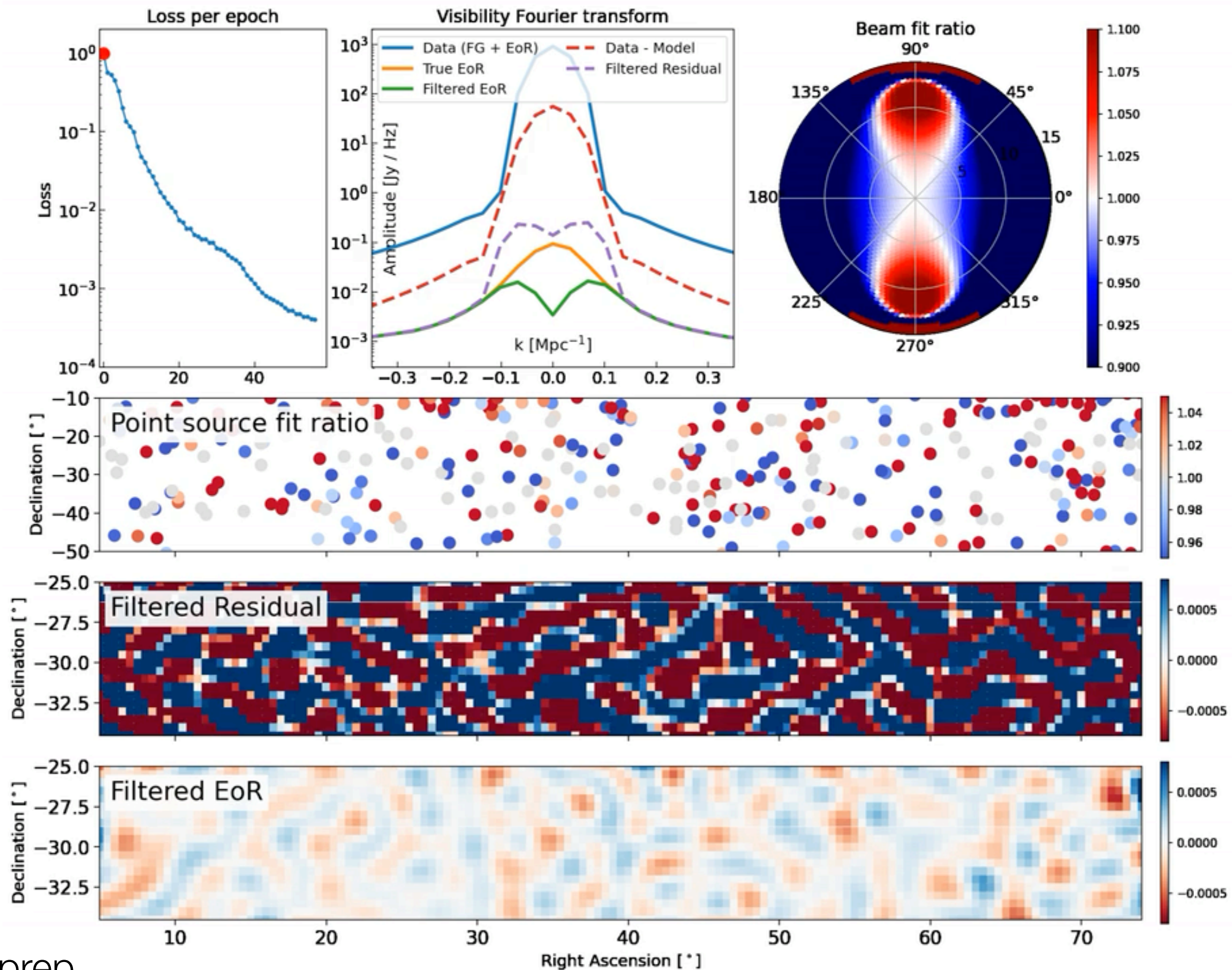
# How to make it differentiable?





# Example with an interferometer

point source + beam optimization



For now: testing degeneracies

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**Posterior** expansion via the Fisher matrix (aka the -Hessian)

$$F_{ij} = - \frac{\partial^2 \ln P}{\partial \theta_i \partial \theta_j}$$

Can compute the Hessian exactly via automatic diff.

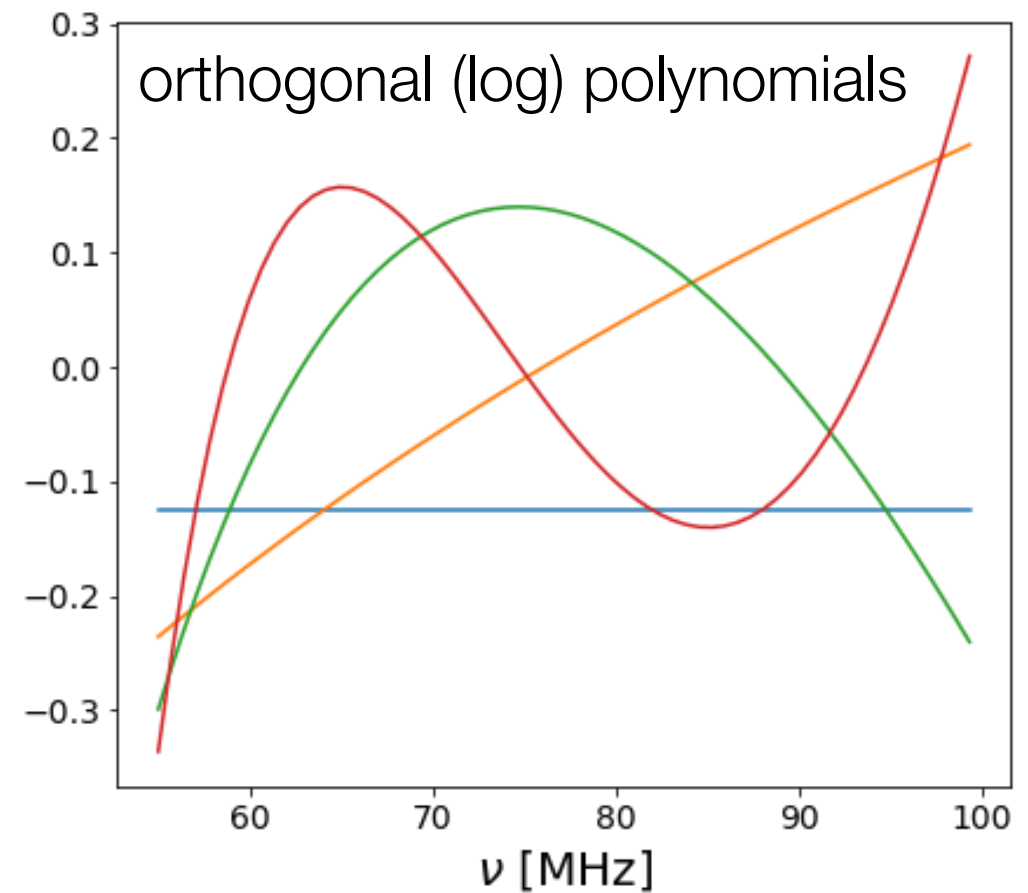
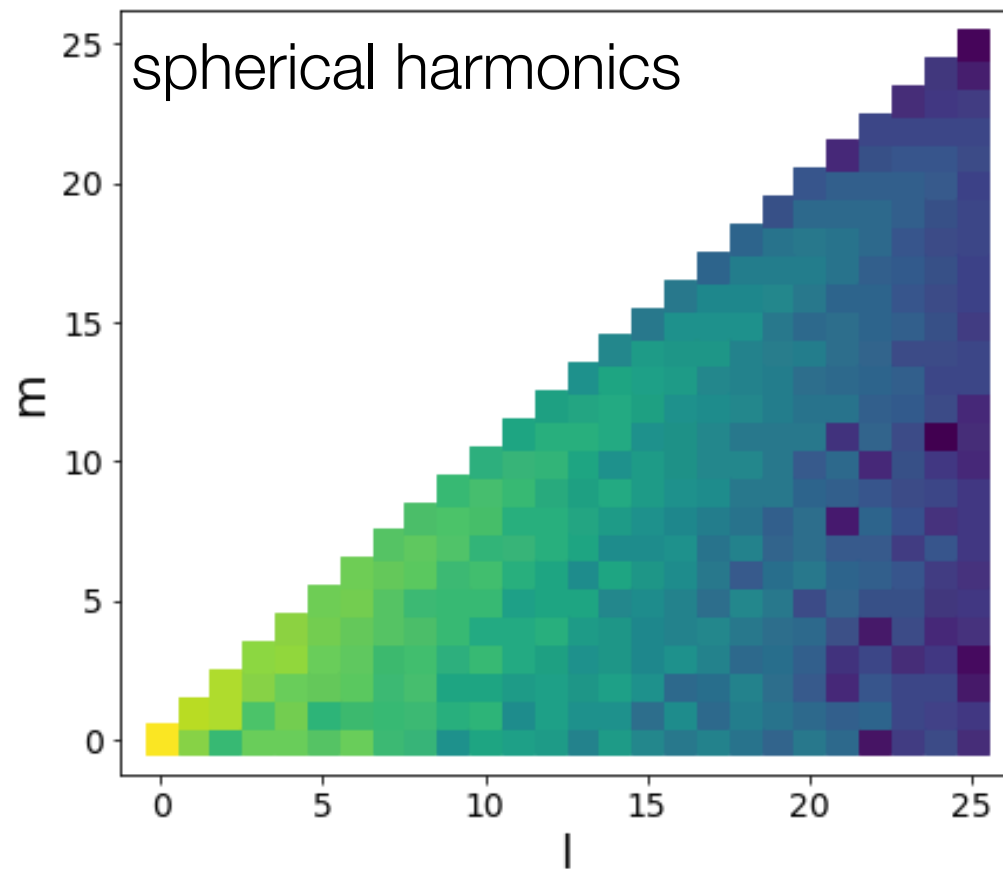
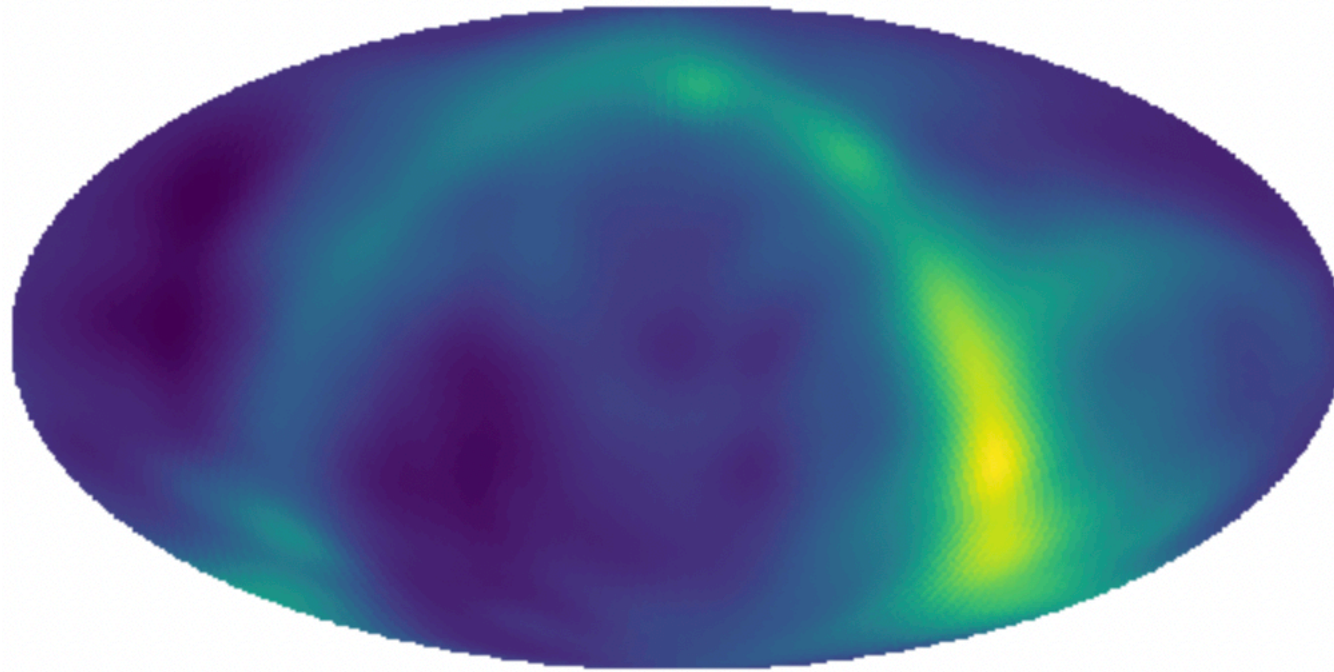
$$C_{ij} = [F^{-1}]_{ij}$$

T <sub>21</sub>	T×F	T×B
	FG	F×B
		B

The full F inverse accounts for degeneracies between T21, FG, and beam.

No noise and no front-end calibration in these tests.

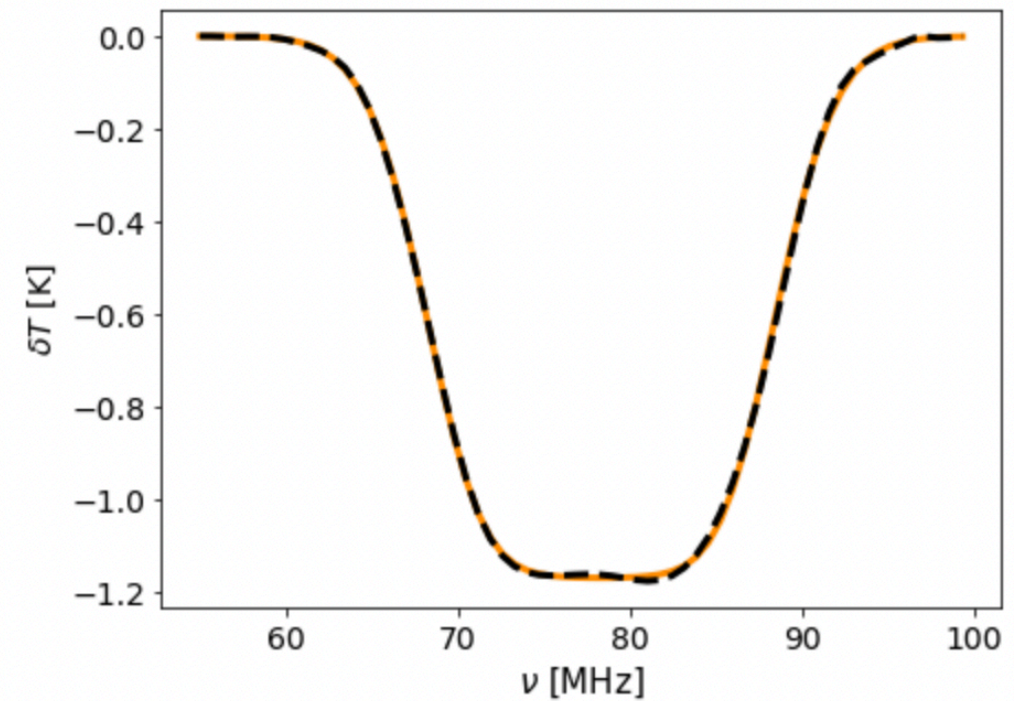
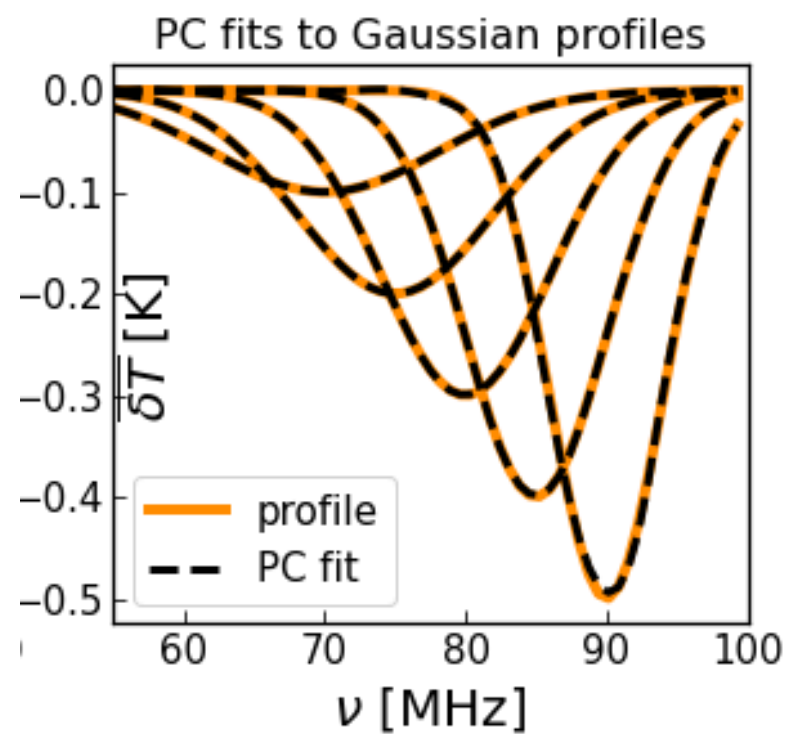
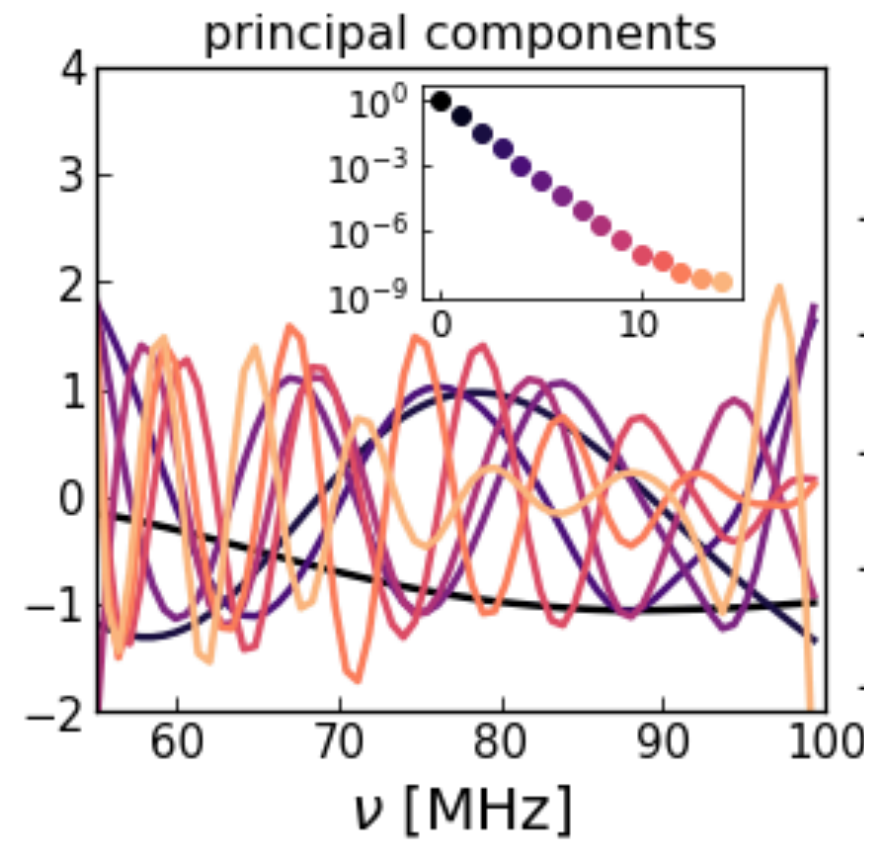
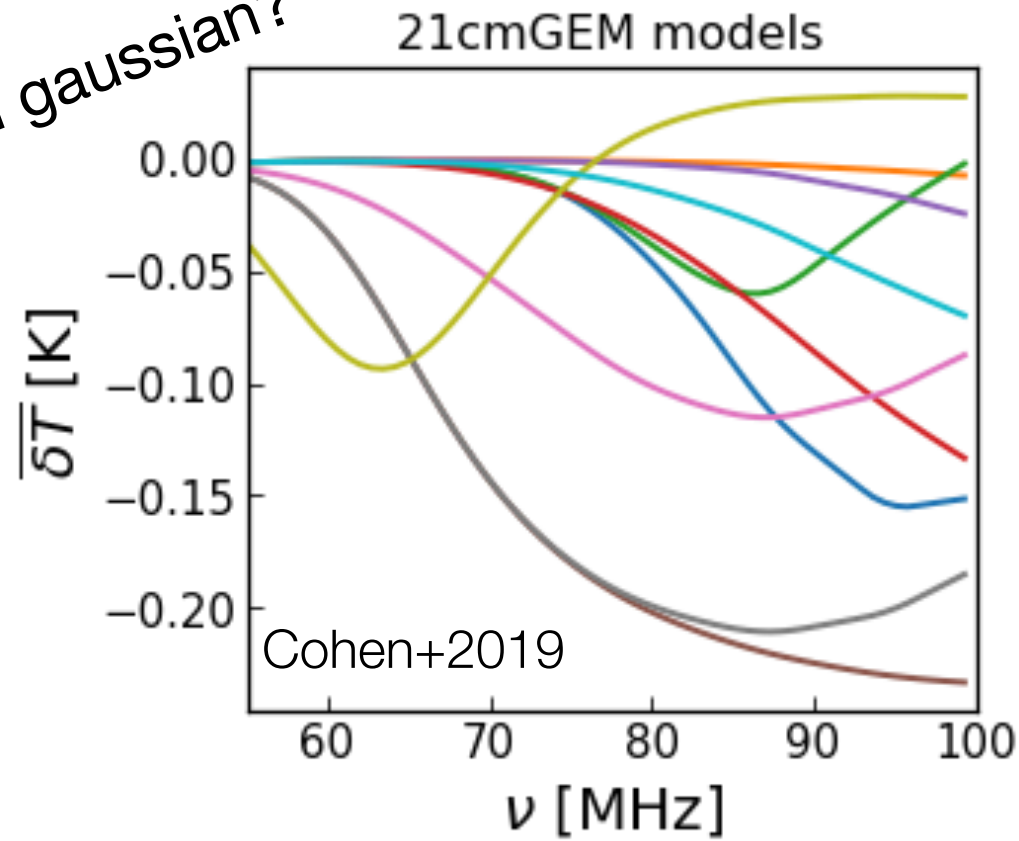
# Foreground parameterization



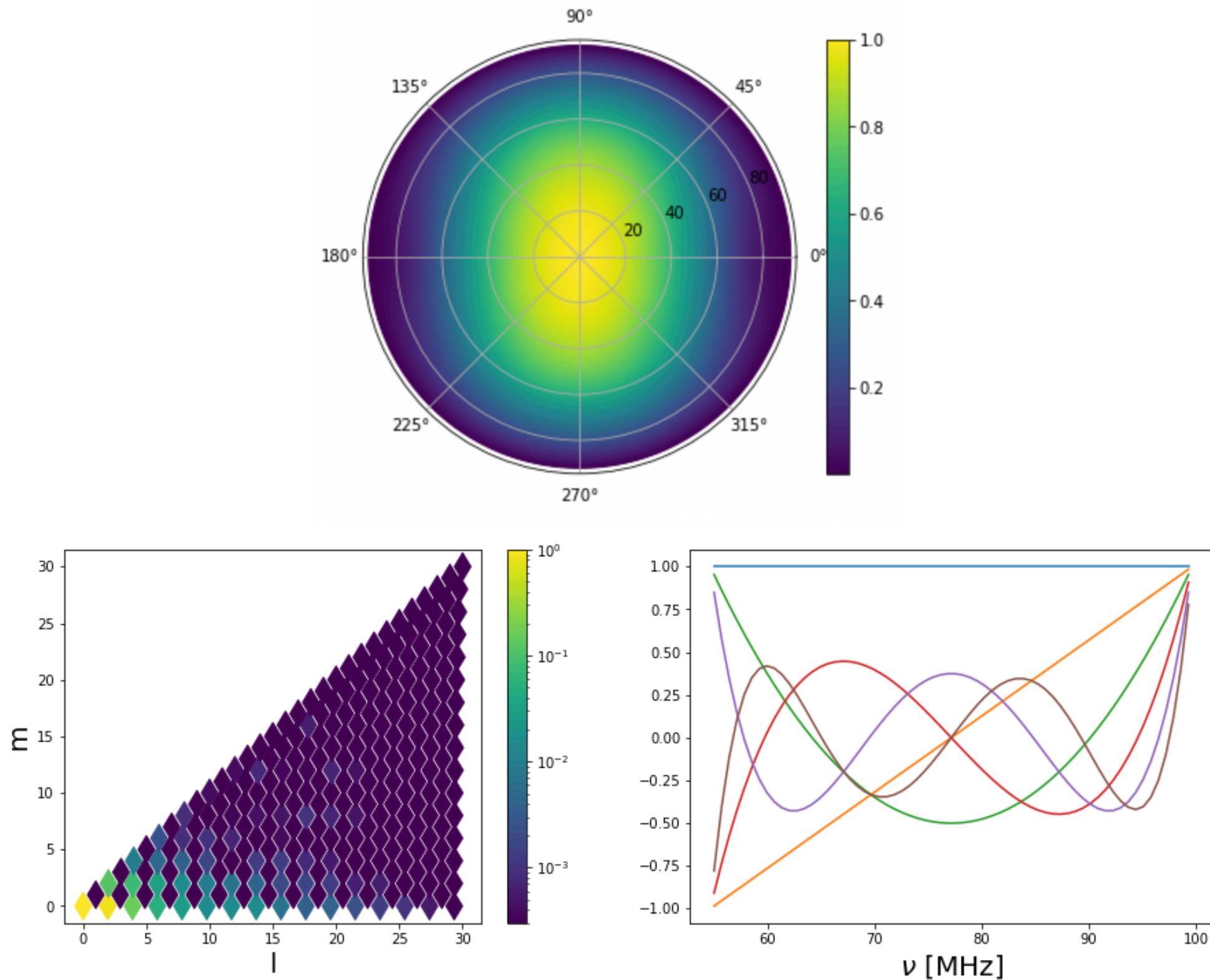


# 21 cm parameterization

flattened gaussian?

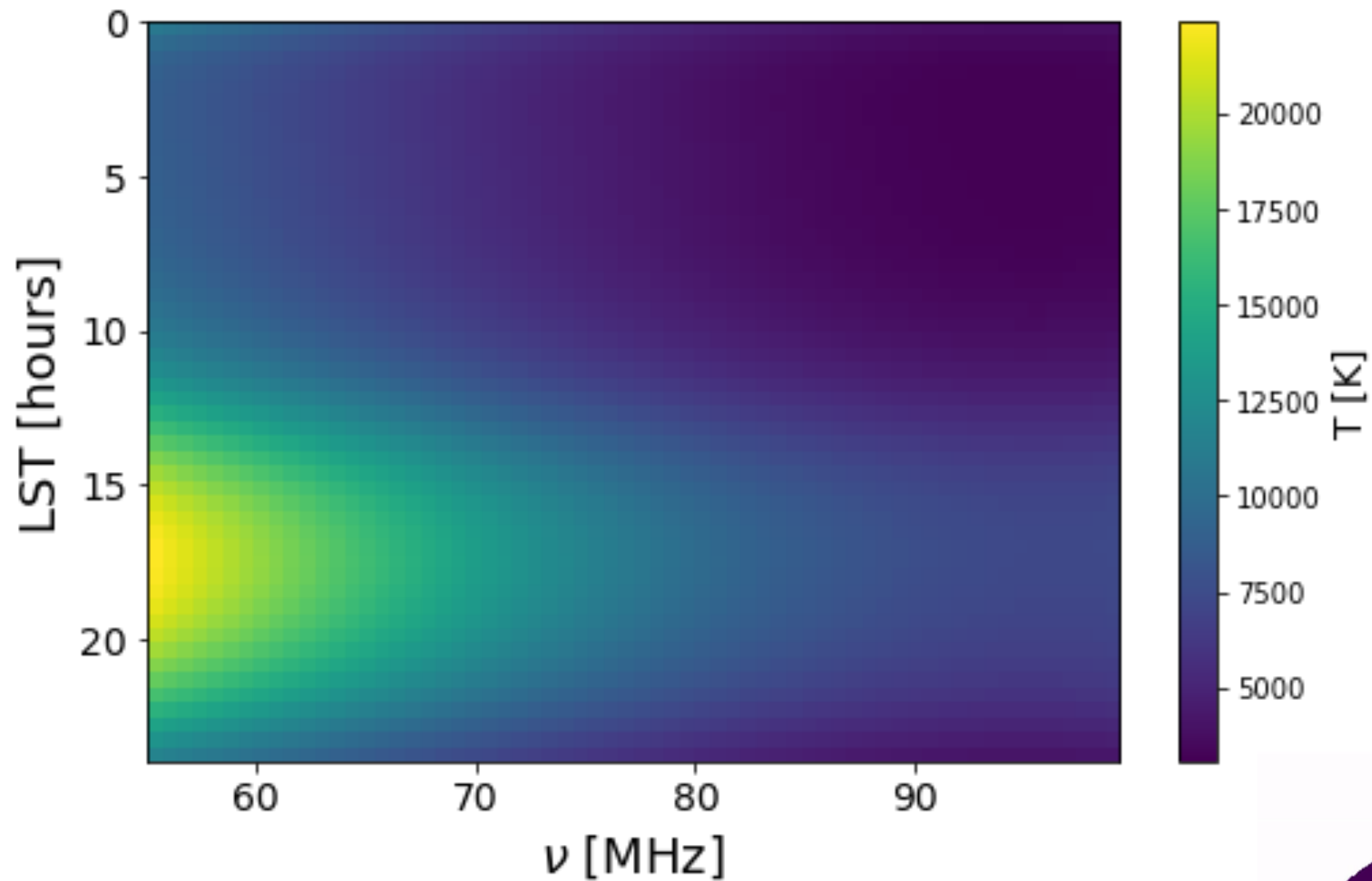


# Instrument parameterization: EDGES beam

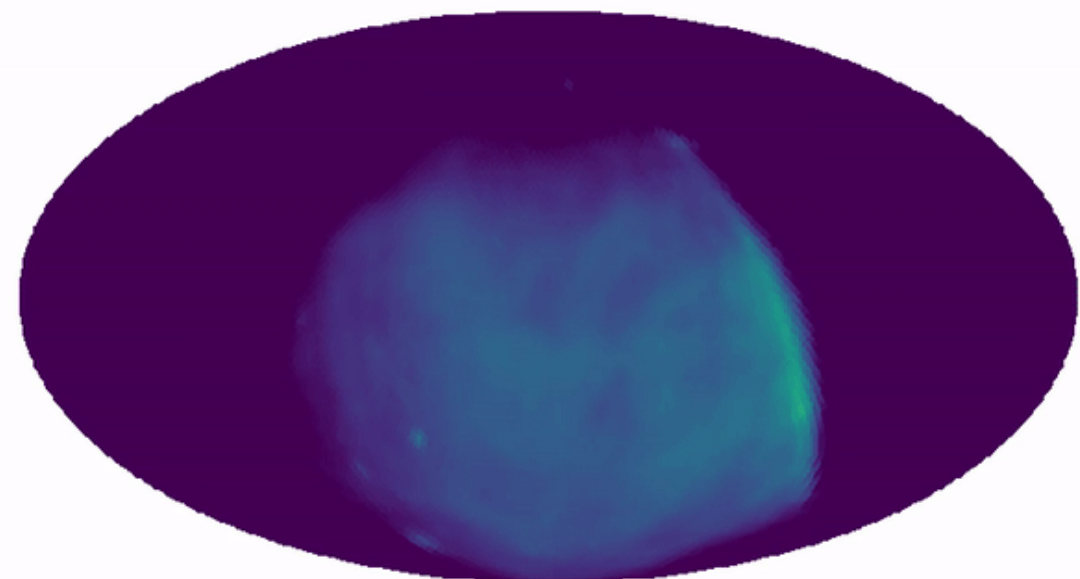




# Mock observation setup

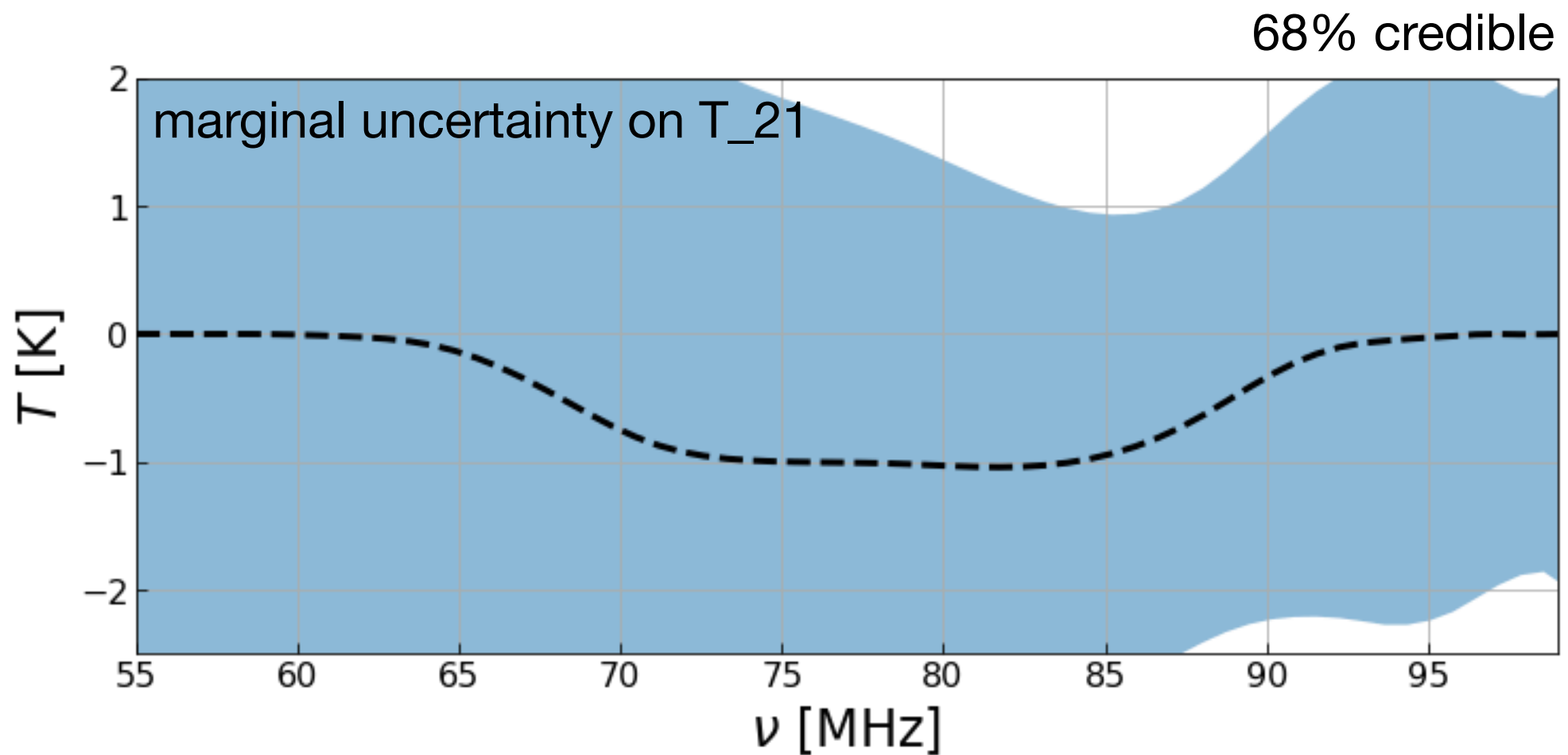


Nfrequency = 64  
Ntimes = 50  
Npixel = 12288 (NSIDE=32)  
no noise, no calibration



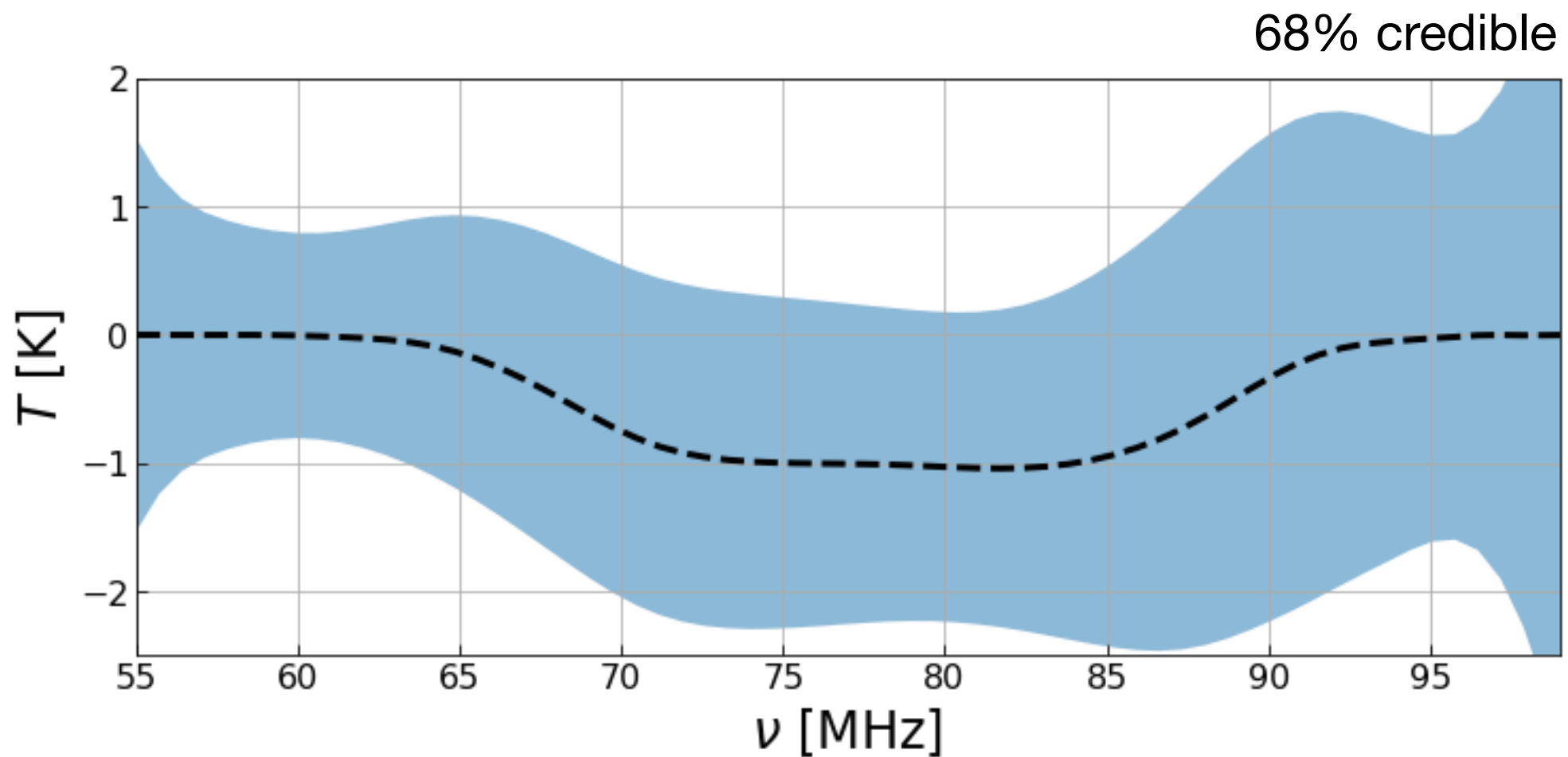
# Testing for degeneracies

- **T\_21** (no prior), **Beam** (no prior), FG (known)
- 1 LST



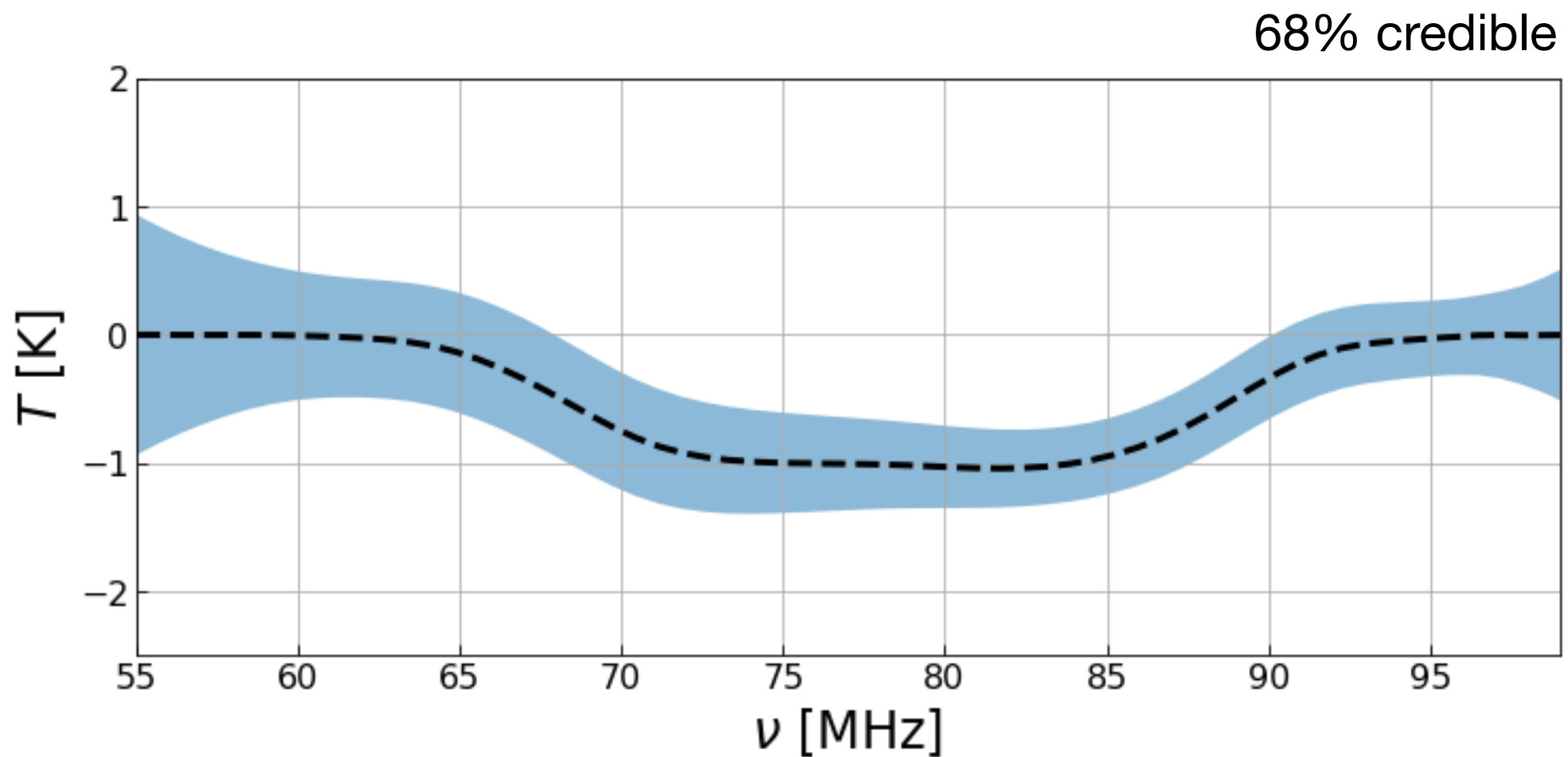
# Testing for degeneracies

- **T\_21** (2 K prior), **Beam** (1% prior), FG (known)
- 1 LST



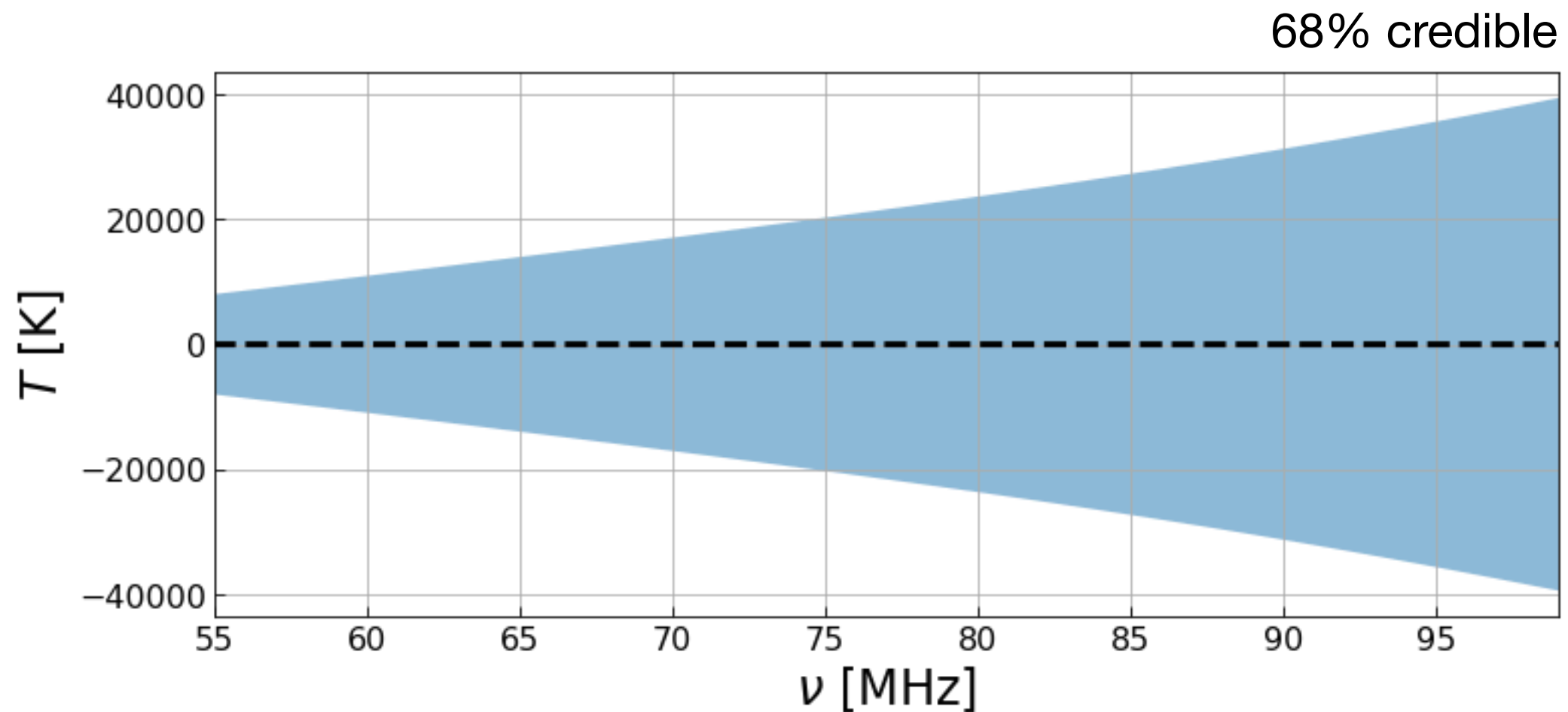
# Testing for degeneracies

- **T\_21** (2 K prior), **Beam** (1% prior), FG (known)
- 24 hours LST



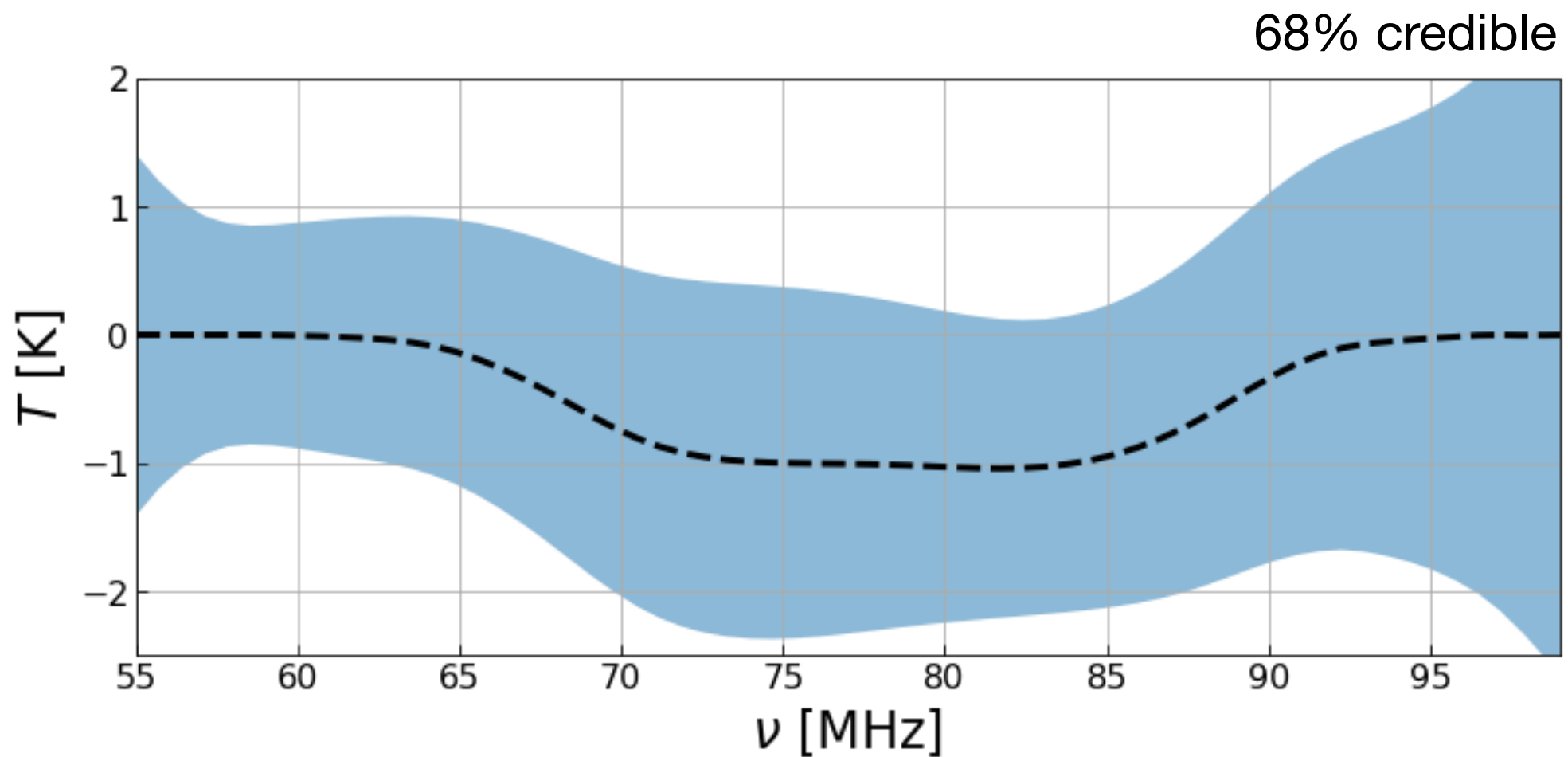
# Testing for degeneracies

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# Testing for degeneracies

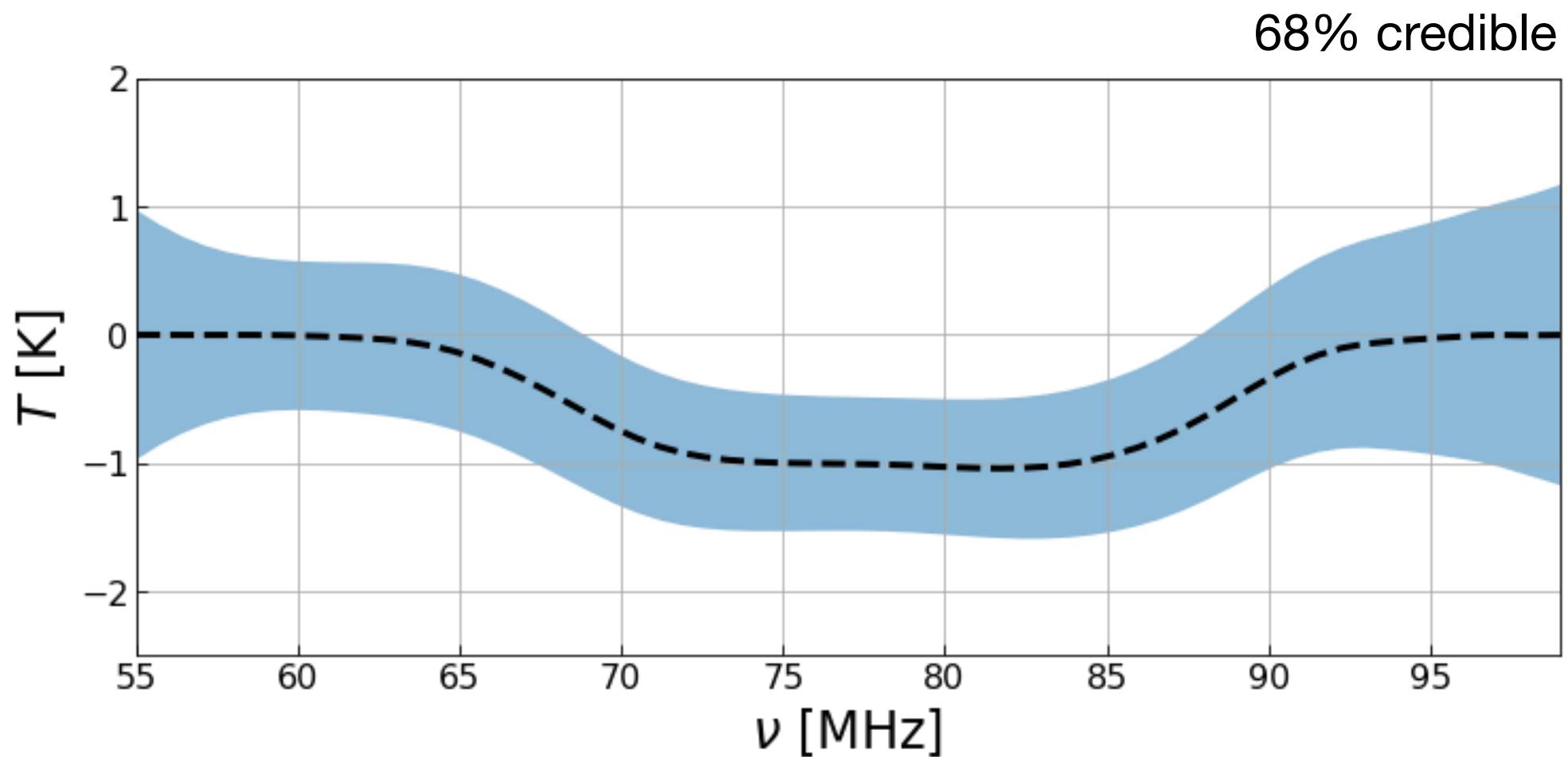
- **FG** (10% prior), **T\_21** (2 K prior), Beam (known)
- 24 hours LST





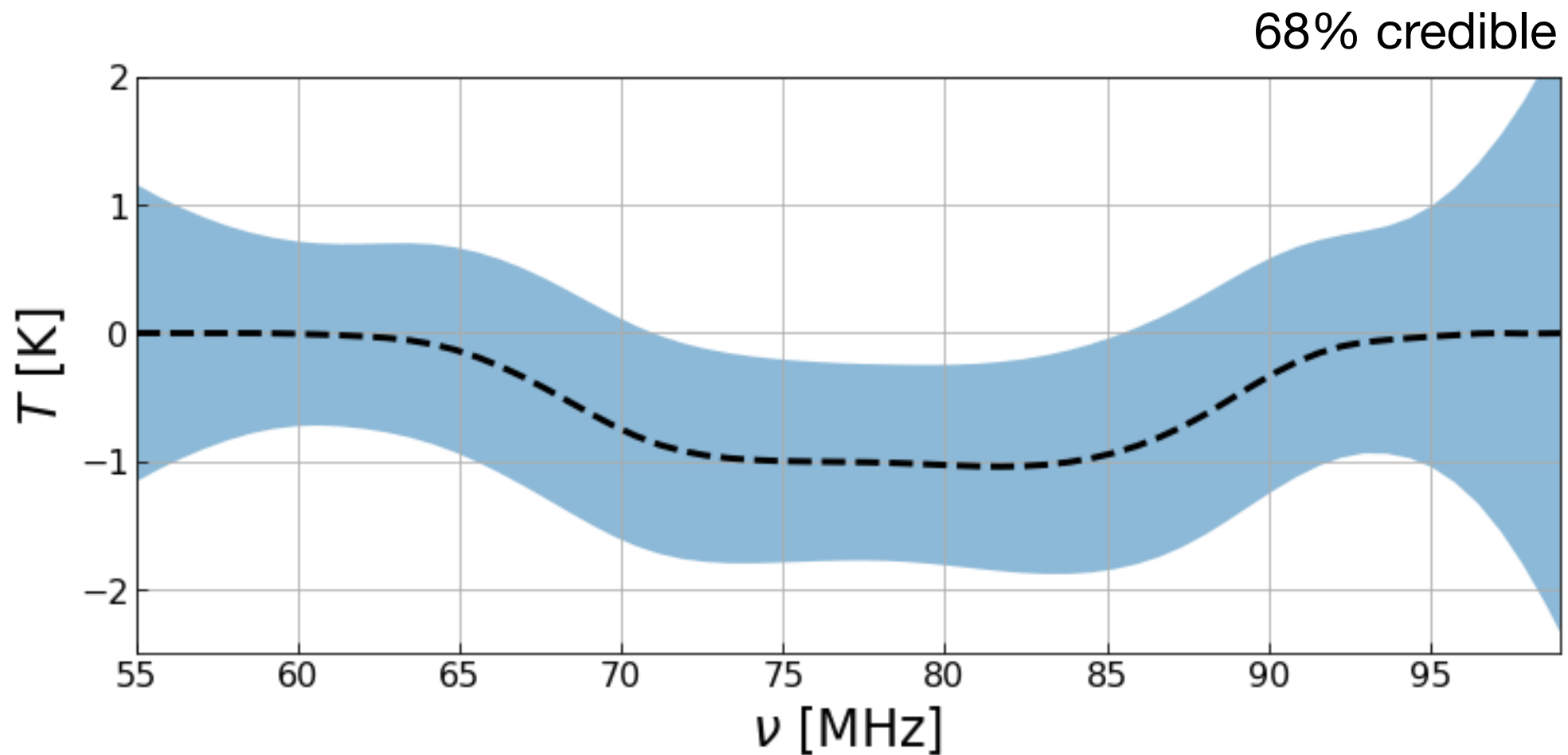
# Testing for degeneracies

- **FG** (10% prior,  $m > 0$ ), **T\_21** (2 K prior), Beam (known)
- 24 hours LST



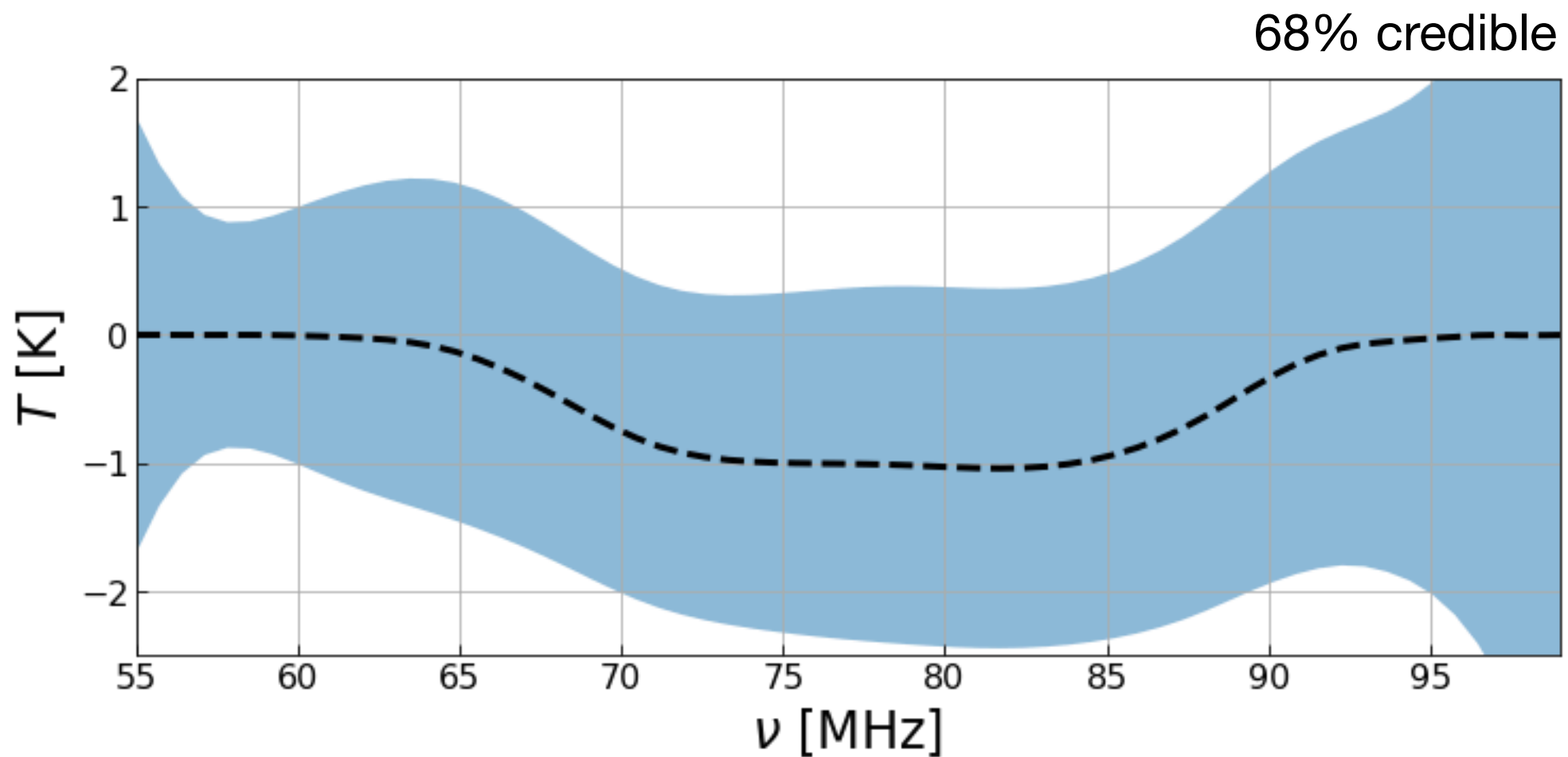
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# Testing for degeneracies

- **FG** (10% prior,  $m > 0$ ), **T\_21** (2 K prior), **Beam** (1% prior)
- 1 LST



# Some avenues for progress?

- Down-weight  $m=0$  angular modes with a FG spatial covariance (e.g. Liu et al. 2012)

*Do we even know this covariance accurately?*

*Requires more complex observations (smaller beams, steerable pointing)*

- Set a prior on the global signal with a  $P(k)$  detection

*This is model dependent*

# Summary

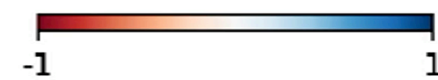
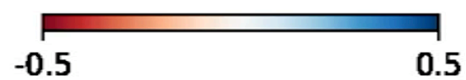
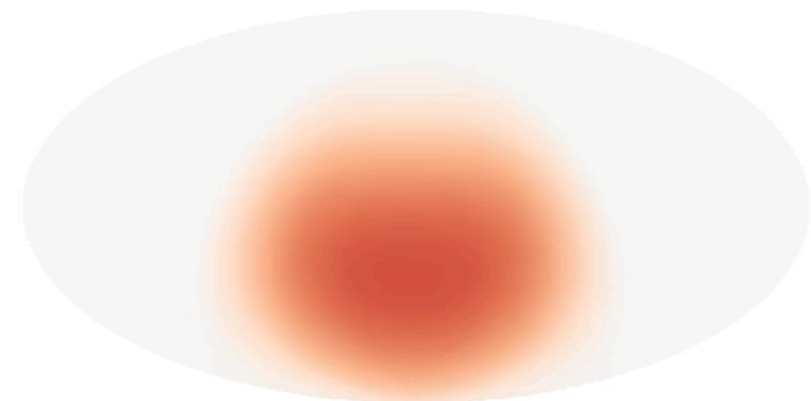
- Forward modeling is key to a deeper understanding of **degeneracies** between the signal and systematics, and for fully leveraging the **statistical power** in the data (e.g. multi-LSTs). More results on optimization and sampling to come soon...
- Even in ideal circumstances (i.e. perfect front-end calibration, perfect beam knowledge, and multi-LSTs), “detection” of a 21 cm global signal is complicated by degenerate FG modes

# Cool features: gradient maps

Snapshot gradient

Accumulated gradient

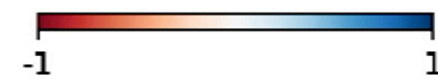
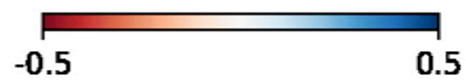
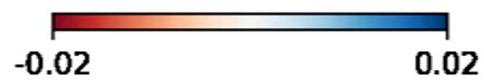
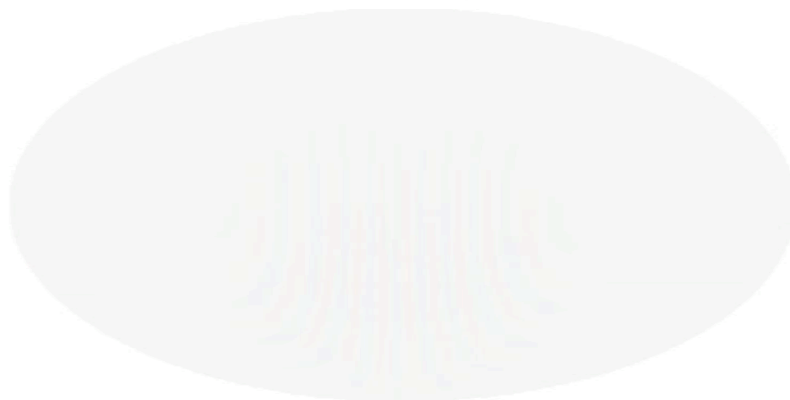
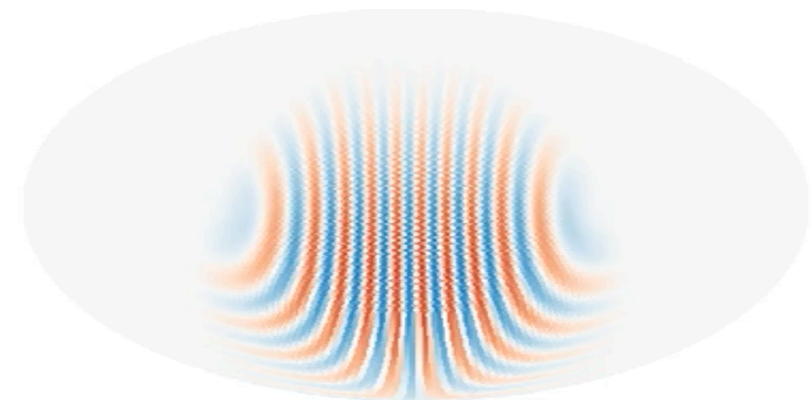
Perturbation



Snapshot gradient

Accumulated gradient

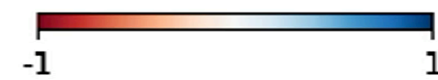
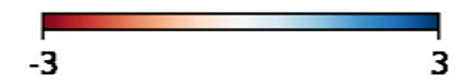
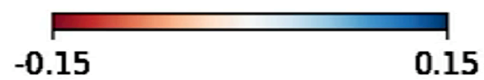
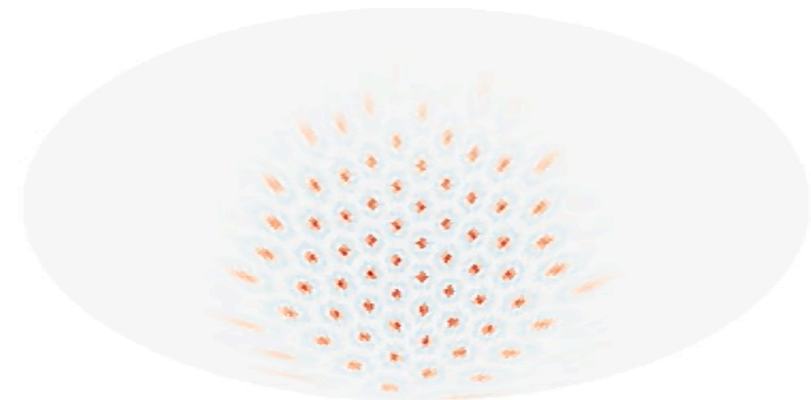
Perturbation



Snapshot gradient

Accumulated gradient

Perturbation





# Performance

Forward Model Runtime with Gradients

